
From the Selected Works of Boukhemis Chetate

October, 2006

Choice of Input Data Type of Artificial Neural Network to Detect Faults in Alternative Current Systems

Tarak Benslimane
Boukhemis Chetate



Available at: https://works.bepress.com/boukhemis_chetate/S/

Choice Of Input Data Type Of Artificial Neural Network To Detect Faults In Alternative Current Systems

¹ T. Benslimane, ² B. Chetate and ³ R. Beguenane

^{1,2} Research Laboratory of Electrification in Industrial Enterprises, University of Boumerdes, Algeria

³ Groupe ERMETIS, Département des sciences appliquées, Université du Québec à Chicoutimi, Canada

Abstract: This paper present a study on different input data types of ANN used to detect faults such as over-voltage in AC systems (AC network , induction motor). The input data of ANN are AC voltage and current. In no fault condition, voltage and current are sinusoidal. The input data of the ANN may be the instantaneous values of voltage and current, their RMS values or their average values after been rectified. In this paper we presented different characteristics of each one of these data. A digital software C++ simulation program was developed and simulation results were presented.

Keywords: Diagnosis, Learning Data type, AC voltage and current, instantaneous value, RMS value, Average value.

INTRODUCTION

AC systems (AC network , induction motor) may be exposed to different kinds of faults (over-voltage, single phasing, under-voltage, unbalance state). These faults need to be detected and identified rapidly in order to take the appropriate procedure to protect the AC system. That is possible by using the artificial neural network. This former need input data in its conception and to be used after that. The input data must be significantly sensible to all faults that happen.

Choice of data type (mathematical models and simulation results)

The simulation is done by using the software programming language C++ with following parameters: $V_{rms} = 115.45 \text{ V} \ \& \ 220 \text{ V}$, 50 Hz , Sample time $T=0.0001$ seconds.

Sinusoidal instantaneous value of voltage and current

AC systems diagnosis may be presented by the following scheme :

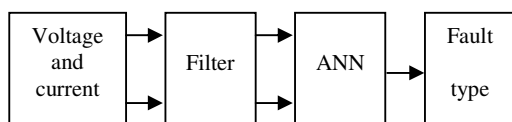


Fig. 1 Schematic diagram of fault detection in AC system

In the following part, we will simulate the over-voltage and thus we will consider only the voltage signal as an input of the ANN. Voltage is acquired in sample time of T (fig. 2). Then, It is filtered to get the sinusoidal fundamental component which will be introduced to the ANN to detect the fault type.

In this case, if T_s is the signal period and T is the simple time, there will be $((T_s/T)+1)$ per period value that will be introduced to faults detection ANN to conceive it. By the other hand, when the ANN model is completed, the fault detection (for example over-voltage) is done

instantaneously (without delay time). This data type is sensible to all kinds of faults even very short time ones (pulses).

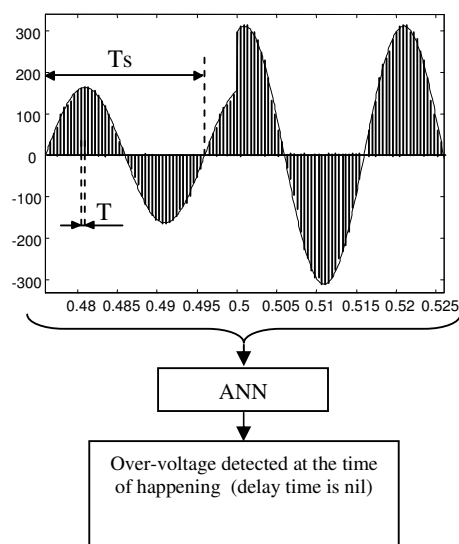


Fig. 2 Schematic diagram of over-voltage detection by using instantaneous values of voltage

RMS value of Sinusoidal voltage

RMS value per period

Numerical integration

In this case, RMS value of sinusoidal voltage is calculated and introduced to the ANN to detect the faults.

RMS value of sinusoidal signal of T_s as period can be calculated as follow:

$$V_{rms}^2 = \frac{1}{T_s} \int_0^{T_s} V^2(t) dt \quad (1)$$

Numerically, RMS value can be calculated by:

$$V_{rms}^2 = \frac{1}{T_s} \sum_{i=1}^N V_i^2 T \quad (2)$$

where:

V_i is the voltage at time $t=i$,

T is the sampling time,

N is the number of sample voltage values taken per period:

$$N = \frac{T_s}{T} + 1 \quad (3)$$

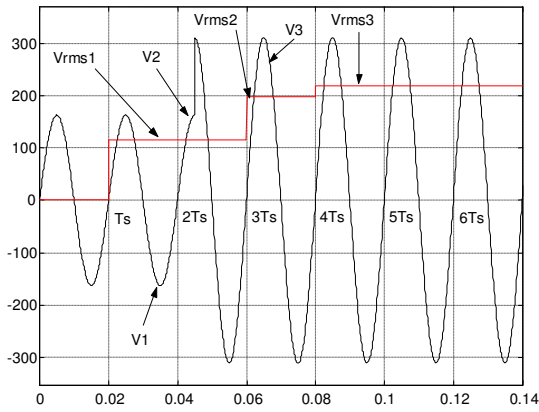


Fig. 3 Simulation result of over-voltage influence on RMS value of voltage calculated by numerical integration method

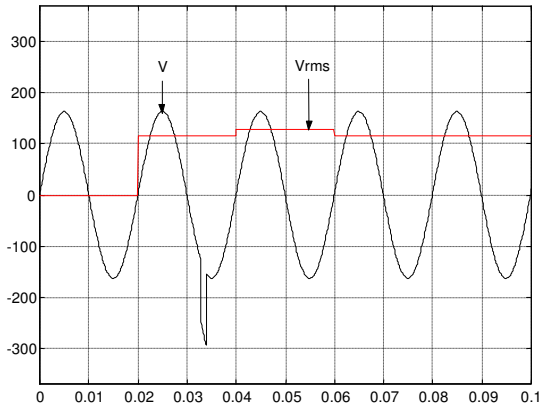


Fig. 4 Simulation result of sensibility of RMS value of voltage calculated by numerical integration method

The RMS value of sinusoidal voltage is always given at the end of each period (fig 3). The voltage V is defined like follow:

$$V = \begin{cases} V1 & 0 < t < 2Ts \\ V2 & 2Ts < t < 3Ts \\ V3 & 3Ts < t < 6Ts \end{cases} \quad (4)$$

After calculating its RMS value using this method, we get:

$$V_{rms} = \begin{cases} 0 & 0 < t < Ts \\ V_{rms1} & Ts < t < 2Ts \\ V_{rms1} & 2Ts < t < 3Ts \\ V_{rms2} & 3Ts < t < 4Ts \\ V_{rms3} & 4Ts < t < 5Ts \\ V_{rms3} & 5Ts < t < 6Ts \end{cases} \quad (5)$$

As said before, it is clear that the RMS value of the voltage is always got at the end of each period. When an over-

voltage occurs at a any time between nTs and $(n+1)Ts$, there will be an increase in the RMS value that is recovered at $(n+1)Ts$ with a varying delay time between 0 and Ts . This delay time, wasted in calculation of RMS value, added to the time of execution of the ANN program increase the time between the fault and its detection.

This data type is sensible to all kinds of faults but more the fault is shorter in time (pulses) more its influence is limited and so its detection is difficult (fig. 4).

Discrete Fourier Transform (DFT)

As the precedent method, the RMS value of sinusoidal voltage is calculated in one period (T_s). Discrete Fourier Transform(DFT) algorithm is used to calculate peak values from sampled voltage. 8 samples per cycle (period) are taken for the calculation It is calculated like follow [1]:

Sampled values of voltage = V_1, V_2, \dots, V_8 .
Real coefficients for 8 samples (R_i) = 0, .707, 1, 0.707, 0, -0.707, -1, -0.707.

Imaginary coefficients for 8samples (I_i) = 1, 0.707, 0, -0.707, -1, -0.707, 0, 0.707.

Real part of the voltage:

$$V_R = \frac{1}{4} \sum_{i=1}^8 R_i V_i \quad (6)$$

$$= \frac{1}{4} (0 \cdot V_1 + 0.707 \cdot V_2 + \dots - 0.707 \cdot V_8).$$

Imaginary part of the voltage:

$$V_I = \frac{1}{4} \sum_{i=1}^8 I_i V_i \quad (7)$$

$$= \frac{1}{4} (1 \cdot V_1 + 0.707 \cdot V_2 + \dots + 0.707 \cdot V_8).$$

Peak value is given by:

$$V_{peak} = \sqrt{V_R^2 + V_I^2} \quad (8)$$

RMS values of voltage is calculated by:

$$V_{rms} = \frac{\sqrt{2}}{2} V_{peak} = 0.707 V_{peak} \quad (9)$$

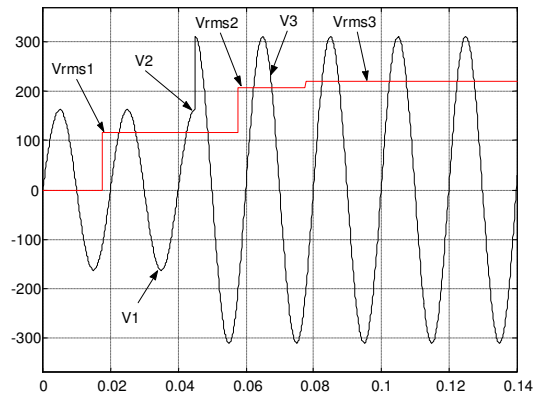


Fig. 5 Simulation result of over-voltage influence on RMS value of voltage calculated by Discrete Fourier Transform method (DFT)

The voltage V is defined like follow:

$$V = \begin{cases} V1 & 0 < t < 0.04 \\ V2 & 0.04 < t < 0.06 \\ V3 & 0.06 < t < 0.12 \end{cases} \quad (10)$$

After calculating its RMS value using this method, we get:

$$V_{rms} = \begin{cases} 0 & 0 < t < 7 \cdot T_s / 8 \\ V_{rms1} & 7 \cdot T_s / 8 < t < 7 \cdot T_s / 8 + 2T_s \\ V_{rms2} & 7 \cdot T_s / 8 + 2T_s < t < 7 \cdot T_s / 8 + 3T_s \\ V_{rms3} & 7 \cdot T_s / 8 + 3T_s < t < 7 \cdot T_s / 8 + 4T_s \\ V_{rms3} & 7 \cdot T_s / 8 + 4T_s < t < 7 \cdot T_s / 8 + 5T_s \end{cases}$$

It is clear that the RMS value of the voltage is always got at $((7 \cdot T_s / 8) + (n \cdot T_s))$ (fig. 5). When an over-voltage occurs at a any time between $((7 \cdot T_s / 8) + (n \cdot T_s))$ and $((7 \cdot T_s / 8) + ((n+1) \cdot T_s))$, there will be an increase in the RMS value that is recovered at $((7 \cdot T_s / 8) + ((n+1) \cdot T_s))$ with a varying delay time between 0 and T_s . This delay time, wasted in calculation of RMS value, added to the time of execution of the ANN program increase the time between the fault and its detection.

This data type is sensible to all kinds of faults unless very short time ones (pulses) that occurs between $(n \cdot T_s / 8)$ and $((n+1) \cdot T_s / 8)$ because there will be no influence on the RMS value of the voltage calculated by DFT method (fig. 6).

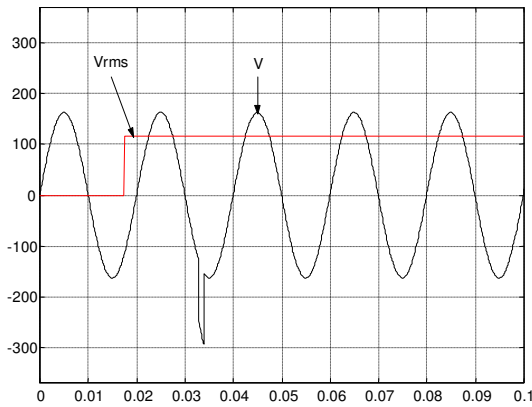


Fig. 6 Simulation result of sensibility of RMS value of voltage calculated by Discrete Fourier Transform method (DFT)

RMS value per half period

By replacing V_i^2 by V_{icar} in the expression (2) we get:

$$V_{rms}^2 = \frac{1}{T_s} \sum_{i=1}^N V_{icar} T = V_{carave} \quad (12)$$

Since V_{icar} is always positive ($V_{icar} = V_i^2$) and according to last mathematical expression (12), it can be said that V_{rms}^2 is the square of average value of the function V_{icar} that is the square of the function V_i . Hence, it is possible to calculate V_{rms} by calculating the average value of the function V_{icar} which has $T_s/2$ as period ($V_{icar} = V_i^2$). So instead of calculation of RMS value of V_i along one period (T_s), it is preferable to calculate the average value of V_i^2 along its period ($T_s/2$) and then we calculate its square root (fig. 7).

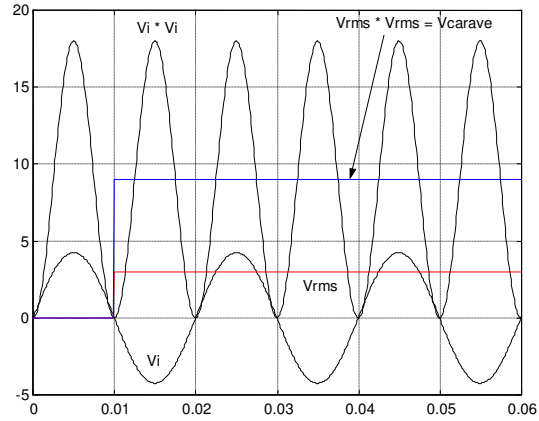


Fig. 7 Simulation result of RMS value of voltage V_i and average value of V_i^2

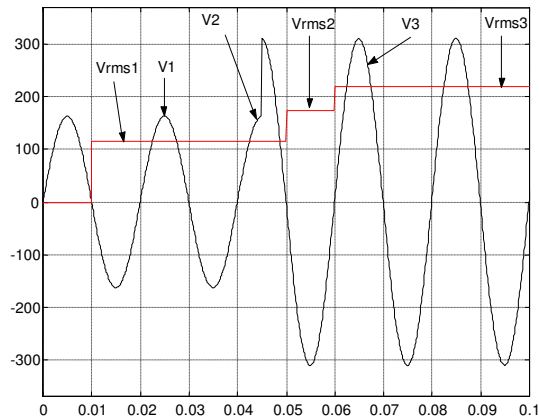


Fig. 8 Simulation result of over-voltage influence on RMS value of voltage based on the average value of its square calculated by numerical integration method

The voltage V is defined like follow:

$$V = \begin{cases} V1 & 0 < t < 0.04 \\ V2 & 0.04 < t < 0.05 \\ V3 & 0.05 < t < 0.10 \end{cases} \quad (13)$$

After calculating its RMS value using this method, we get:

$$V_{rms} = \begin{cases} 0 & 0 < t < 0.01 \\ V_{rms1} & 0.01 < t < 0.05 \\ V_{rms2} & 0.05 < t < 0.06 \\ V_{rms3} & 0.06 < t < 0.1 \end{cases} \quad (14)$$

As said before, it is clear that the RMS value of the voltage is always got at the end of each half period of V ($T_s/2$) (fig. 8). When an over-voltage occurs at a any time between $(nT_s/2)$ and $((n+1)T_s/2)$, there will be an increase in the RMS value that is recovered at $((n+1)T_s/2)$ with a varying delay time between 0 and $T_s/2$.

This data type is sensible to all kinds of faults but more the fault is shorter in time (pulses) more its influence is limited and so its detection is difficult (fig. 9).

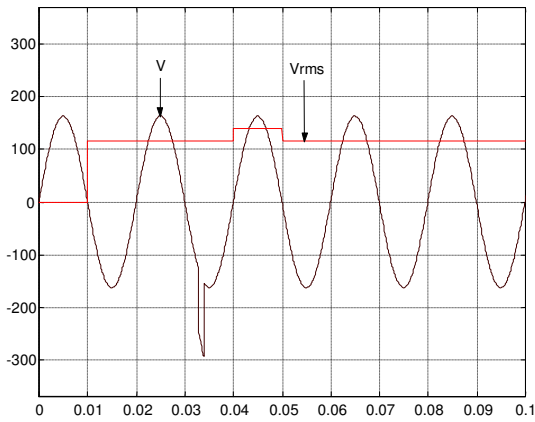


Fig. 9 Simulation result of sensibility of RMS value of voltage based on the average value of its square calculated by numerical integration method

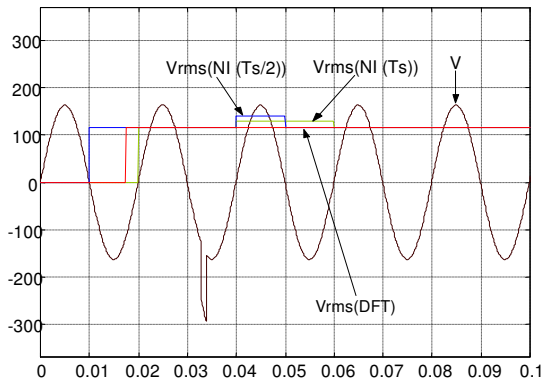


Fig. 10 Simulation result of comparison of sensibilities of RMS values of voltage calculated by different methods

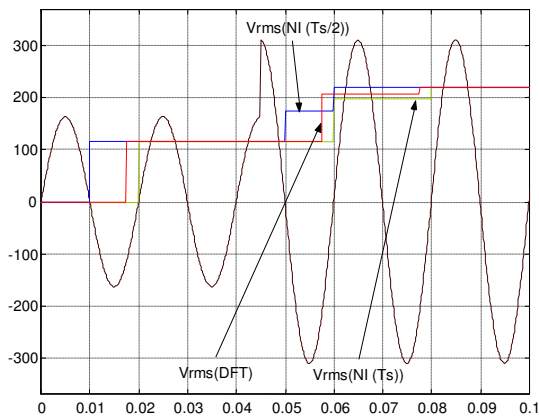


Fig. 11 Simulation result of comparison of over-voltage influence on RMS values of voltage calculated by different methods

In figure 10 are compared the sensibilities of RMS values of voltage calculated by different methods. It's clear that the RMS value of voltage based on the average value of its square calculated by numerical integration method (Vrms NI(Ts/2)) is the most sensible to short variations. While the RMS value of voltage calculated by numerical integration method (Vrms NI(Ts)) is less sensible and the

RMS value of voltage calculated by DFT method (Vrms (DFT)) is the least sensible to short time variations.

Average value of rectified voltage

In this case, voltage is filtered and rectified. The average value of output signal of the rectifier is calculated and introduced to the ANN to detect the fault (fig. 12) [2].

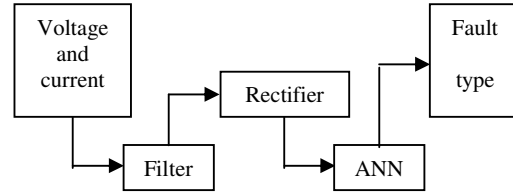


Fig. 12 Schematic diagram of fault detection in AC system based on average value of rectified voltage

The rectifier may be realized hardly or softly.

The mathematical expression that allows the calculation of the average value of rectified voltage is:

$$V_{ave} = \frac{1}{T_s/2} \int_0^{T_s/2} V(t) dt \quad (15)$$

Numerically, this average value can be calculated by:

$$V_{ave} = \frac{1}{T_s/2} \sum_{i=1}^{N'} V_i T \quad (16)$$

where :

V_i is the voltage at time $t=i$,

T is the sampling time,

N' is the number of sample voltage values taken per half period:

$$N' = \frac{T_s/2}{T} + 1 \quad (17)$$

The mathematical expression linking this average value to the maximal value is:

$$V_{ave} = 2 \frac{V_{max}}{\pi} \quad (18)$$

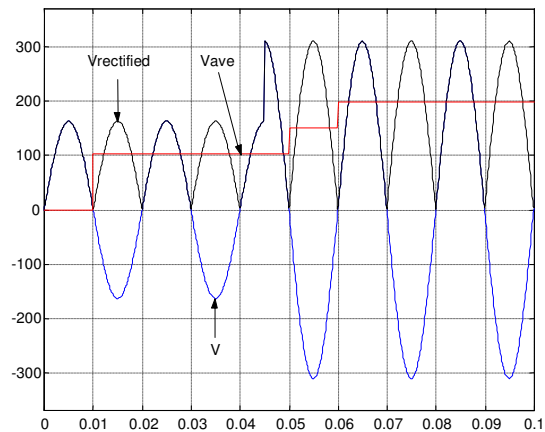


Fig. 13 Simulation result of over-voltage influence on average value of rectified voltage

CONCLUSION

In this paper, are presented the different data inputs of ANN used to detect faults (over-voltage) in AC systems. These data are compared at different levels such as sensibility to fault and delay time of influence of fault on the data. The ANN input data is selected according to the application.

REFERENCES

1. S. R. Kolla and L. Varatharasa, 2000 "Identifying three-phase induction motor faults using artificial neural networks," *ISA Transactions*, Vol. 39, pp. 433-439
2. Mesure de tension efficace vrai 2005 (true rms _ root-mean-square), crête et moyenne, *Actualités du test, de la mesure et de l'électronique-le journal T&M électronique gratuit du net.*

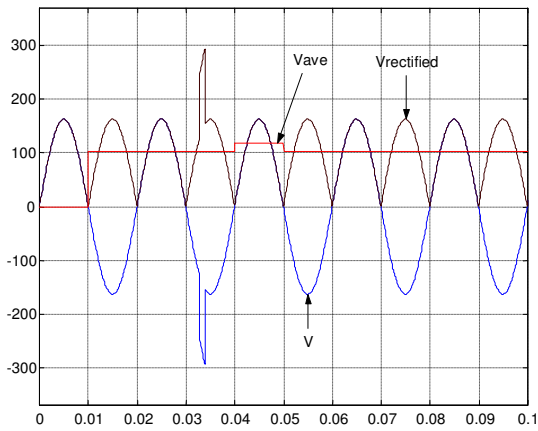


Fig. 14 Simulation result of sensibility of average value of rectified voltage calculated by numerical integration method

As said before, it is clear that the average value of the rectified voltage is always got at the end of each half period of V ($T_s/2$) (fig. 13). When an over-voltage occurs at a any time between ($nT_s/2$) and $((n+1)T_s/2)$, there will be an increase in the average value that is recovered at $((n+1)T_s/2)$ with a varying delay time between 0 and $T_s/2$. This data type is sensible to all kinds of faults but more the fault is shorter in time (pulses) more its influence is limited and so its detection is difficult (fig. 14). The following table, recapitulate the performances of each one of the data types mentioned before.

Table 1: Performances of the different data types

Input data type	Sensibility data to short time fault	Delay time (between fault happening time and data calculation time)
Instantaneous value	Very high	0
RMS value by numerical integration	Average	between 0 and T_s
RMS value by DFT	Low	between 0 and T_s
RMS value based on the average value of square of voltage by numerical integration	High	between 0 and $T_s/2$
Average value of rectified voltage by numerical integration	High	between 0 and $T_s/2$